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4 Goldstein 8.26 4.1 Part (a) In the given con guration, both springs elongate or compress by the same magnitude. Suppose q denotes the position of the mass m from the left end. At $t = 0$, $q(0) = a/2$, but the unstretched lengths of both springs are given to be zero. Therefore, the elongation (compression) of spring k_1 is q and the compression (elongation) of spring k_2 is q . The potential energy ...

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Goldstein Chapter 1 Derivations Michael Good June 27, 2004 1 Derivations 1. Show that for a single particle with constant mass the equation of motion implies the following differential equation for the kinetic energy: $dT/dt = \mathbf{F} \cdot \mathbf{v}$ while if the mass varies with time the corresponding equation is $d(mT)/dt = \mathbf{F} \cdot \mathbf{p}$. Answer: $dT/dt = d(1/2 mv^2)/dt = mv \cdot v' = ma \cdot v = \mathbf{F} \cdot \mathbf{v}$ with time variable mass, d ...

Goldstein Chapter 1 Derivations - Michael R.R. Good

The constraint that the mass is on the wedge is $r = R + l(\cos \alpha, \sin \alpha)$, or $x = X + l \cos \alpha$ and $y = l \sin \alpha$ where l is the distance the mass traveled down the wedge. This is one constraint, which we can express as a function of x, y, X as $f = (x - X) \sin \alpha - y \cos \alpha = 0$.

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